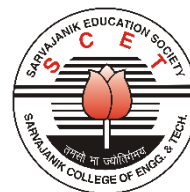




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**Bachelor of Technology**



**B. Tech. Semester IV**

**Subject Name:** Signals and Systems

**Subject Code:** BTEC13401

**Type of course:** PCC

**Prerequisite:** Differential equations and difference equations, Laplace Transform

**Rationale:** The course will create a strong foundation on signals and systems which will be useful for studying analog and digital communication and signal processing. The students will learn basic continuous-time and discrete-time signals and systems. Students will learn the application of various transforms for the analysis of signals and systems both continuous-time and discrete-time. Students will also explore the effect of sampling on the spectrum of a signal.

**Teaching and Examination Scheme:**

Teaching Scheme				Theory Marks			Practical Marks		Total
L	T	P	C	TEE	CA1	CA2	TEP	CA3	150
3	0	2	4	60	25	15	30	20	

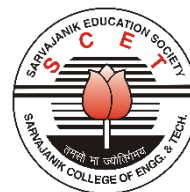
**CA1:** Continuous Assessment (assignments/projects/open book tests/closed book tests) **CA2:** Sincerity in attending classes/class tests/ timely submissions of assignments/self-learning attitude/solving advanced problems **TEE:** Term End Examination **TEP:** Term End Practical Exam (Performance and viva on practical skills learned in course) **CA3:** Regular submission of Lab work/Quality of work submitted/Active participation in lab sessions/viva on practical skills learned in course

**Content:**

Sr. no.	Topics	Teaching Hrs.	Module % Weightage
1.	<b>Introduction to Signals &amp; Systems:</b> Basic definitions of signals, Basic elementary signals, Classification of signals, Basic operations on signals, Overview of a Case study of different signals. Basic definitions of systems, Classification of systems, Basic system properties, Overview of a Case study of different systems.	8	15
2.	<b>Review of Continuous-time Transforms (Fourier Series, Fourier Transform and Laplace transform):</b> Fourier Series Representation of Periodic Signals, Waveform Symmetries, Calculation of Fourier Coefficients. The frequency spectrum of aperiodic signals, Fourier Transform, Relation between Laplace Transform and Fourier	8	10



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	Transform, Properties of Fourier transform, Examples of Fourier transform, Properties of Continuous-Time Fourier transform. Limitations of Fourier transform, Laplace transforms, Relation between Laplace Transform and Fourier Transform, Properties of Laplace transform, Examples of Laplace transform.		
3.	<b>Signal Transmission through Linear Systems:</b> Properties of LTI systems, convolution, and correlation of signals, transfer function, signal bandwidth.	6	15
4.	<b>Discrete-Time Fourier Transform (DTFT):</b> Introduction to DTFT, Relation between DTFT and FT, Properties of DTFT, examples of DTFT.	4	10
5.	<b>Z Transform:</b> The z-Transform, Convergence of z-Transform, Properties of z-Transform, Inverse z-Transform, LTI System analysis from Linear Constant Coefficient Difference Equations using z-Transform.	10	20
6.	<b>Analysis of Continuous-time (CT)&amp; Discrete-Time(DT) Linear Time-Invariant (LTI) Systems:</b> Impulse response characterization and convolution for CT- LTI and DT-LTI systems, Properties of LTI systems, LTI systems characterized by Differential and difference equations.	6	20
7.	<b>Sampling &amp; Reconstruction:</b> Representation of digital signals, The Sampling Theorem, Sampling with a zero-order hold, Reconstruction of a signal from its samples using interpolation, Aliasing and its effects.	3	10

**Suggested Specification table with Marks (Theory/Practical):**

% Distribution of Marks					
R Level	U Level	A Level	N Level	E Level	C Level
15	20	20	20	20	5

**Legends:** **R:** Remembrance, **U:** Understanding; **A:** Application, **N:** Analyze, **E:** Evaluate **C:** Create and above Levels (**Revised Bloom’s Taxonomy**)

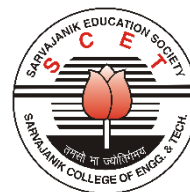
**Note:** This specification table shall be treated as a general guideline for students and teachers. The actual distribution of marks in the question paper may vary slightly from the above table.

**Reference Text Books:**

Sr. No.	Title of book /article	Author(s)	Publisher and details like ISBN	Year of publication	Publication Edition
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1.	Signal and Systems	Anand Kumar	PHI	2012	2 <sup>nd</sup>
2.	Signal and Systems	Alan V. Oppenheim, Alan S. Wilsky and Nawab	Prentice Hall	1983	2 <sup>nd</sup>
3.	Signals and Systems	Simon Haykin and Bary Van Veen	Wiley-India Publications	2002	2 <sup>nd</sup>
4.	Digital Signal Processing Fundamentals and Applications	Li Tan	Elsevier, Academic Press	2013	2 <sup>nd</sup>
5.	Digital Signal Processing	Anand Kumar	PHI	2012	2 <sup>nd</sup>

**Course Outcome:**

Sr. No.	CO Statement After learning this subject students will be able to,	Marks % weightage
CO-1	Explain types of signals, classification and perform various operations on them.	15
CO-2	Analyse linear time-invariant continuous and discrete-time systems.	15
CO-3	Apply transforms for the analysis of signals and systems.	30
CO-4	Carry simulation on signals and systems for observing effects of applying various properties and operations.	20
CO-5	Create a strong foundation of communication and signal processing.	20

**Mapping with POs:**

	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO-1	3	2	1	3	3	1	1	1	1	1	2	1	3	1	2
CO-2	3	2	1	3	3	1	1	1	1	1	2	1	3	1	2
CO-3	3	3	1	3	3	1	1	1	2	1	2	1	3	1	2
CO-4	3	3	2	3	3	2	1	1	2	1	2	1	3	1	2
CO-5	3	2	2	3	3	1	1	1	2	1	2	1	2	1	2

**List of practical:**

1. Introduction to MATLAB as a language/tool and Signal & Systems.
  - a) Enter two variables and find the arithmetic operation between them.
  - b) Write a generalized MATLAB program for Matrix operations.
  - c) Define two variables and Comparison of two variables are equal, greater, or lesser.



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( Using If else)

2. a) Write a MATLAB program to generate and plot different types of continuous and discrete-time signals like Sine, Cosine, Square, Rectangular pulse (using a square function), Sawtooth, and Triangular pulse. The time axis span should be 0 to 200 ms and the amplitude axis between -2 to 2.  
b) Write a MATLAB program to generate and plot continuous-time signals like the Sinc function and Signum function. The time axis span should be -10 to 20 ms and the amplitude axis between -1 to 1.  
Note: Use the subplot command to display CT and DT signals (Two) windows on the same graph.
3. a) Write a MATLAB program to generate and plot basic continuous and discrete-time signals like Impulse, Unit Step, and Unit Ramp signals. The time axis span should be -10 to 10 and the amplitude axis between -1 to 1.  
Note: Use the subplot to display CT and DT signals (Two) windows on the same graph.
4. Plot the signals in the interval  $0 \leq n \leq 2\pi$  using 80 data points.  
 $y(n) = \sin^2 n$ ,  $z = \cos^2 n$ ,  $w = \sin^2 n * \cos^2 n$ ,  $v = \sin^2 n / (0.1 + \cos^2 n)$   
Use the subplot command to display these functions as four windows on the same graph.
5. a) Using the MATLAB plot the function defined by (Consider  $t = -20$  to  $+20$ )  
 $g(t) = 0$  for  $t \leq -5$   
 $= 10 + 2t$  for  $-5 < t < -2$   
 $= 12 + 3t$  for  $-2 < t < 2$   
 $= 22 - 2t$  for  $2 < t < 11$   
 $= 0$  for  $t \geq 11$   
b) Using the MATLAB stem the function defined by (Consider  $n = -20$  to  $+20$ )  
 $x(n) = -4 - 2n$  for  $n [-2:0]$   
 $= -4 + 3n$  for  $n [0:4]$   
 $= 16 - 2n$  for  $n [4:8]$
6. For above  $g(t)$  signal, plot the transformed function  $g(-t)$ ,  $3g(t)$ ,  $-2g(t)$ ,  $g(3/2*t)$ ,  $g(2/3*t)$ .
7. a) From practical 5, take  $x(n)$  as input. Make user-defined Matlab code for the delay and advance shift of the signal.  
b) Using the MATLAB stem the signal  $x[n] = [4 \ 5 \ -4 \ -3 \ 1 \ 2 \ -5 \ 6 \ 3]$ ,  $x[0]=1$ . Using If else instruction makes user-defined code for delay and advance of the signal. Also verify time scaling operation.
8. Over a range of:  $-50 < n < 50$ . Is  $x(n)$  periodic or non-periodic? If periodic then find period theoretically and practically.  
a)  $x(n) = 10 e^{-(n/4)} \sin(3\pi n/16) u(n)$ .  
b)  $x(n) = 2 * \cos(2\pi n/3) - 3 * \sin(\pi n/4)$
9. Using MATLAB find the signal energy for  $x(n) = e^{|n/10|} * \sin(2\pi n/4)$ .
10. Write a MATLAB code to make your function file. Which compares two variables and display two variables are equal, greater, or lesser? ( Use char inbuilt function to display) (Function name is mycompare)  
a) Write a MATLAB code to arrange the array in ascending order.  
(Function name is myascend)  
b) Write a MATLAB code to make your own function file.  
Function  $z = f(x,y)$ ,  $x = f(t)$  and  $y = f(t)$ , where  
 $t = 0:0.1:10$



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$$x = -1 * \sin(t)$$

$$y = 2 * \cos(t)$$

$$z = 2 * x + 2 * y$$

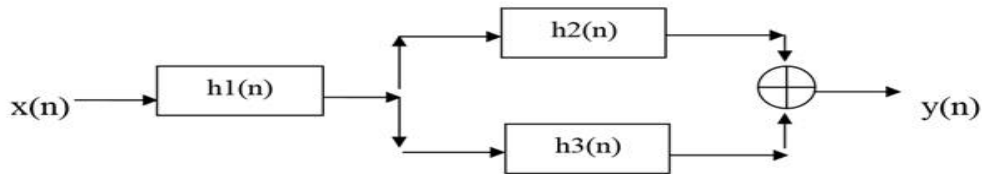
Plot (t,x,t,y,t,z). (Function name is myfunc2)

11. For the signals,
- $$h_1(t) = \sin(3\pi t/16)$$
- $$h_2(t) = 2 \cos(9\pi t/4)$$
- $$h_3(t) = (4/5) * t * u(t)$$
- (Consider  $t = -20$  to  $+20$ )

Verify the different properties of convolution using the “conv” function.

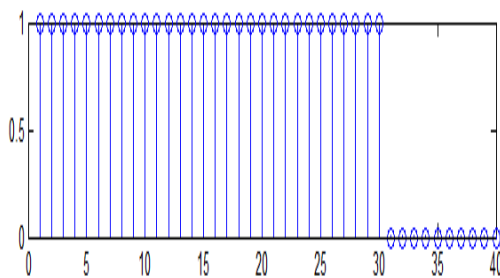
- Commutative -  $h_1(t) * h_2(t) = h_2(t) * h_1(t)$
- Distributive -  $h_1(t) * [h_2(t) + h_3(t)] = h_1(t) * h_2(t) + h_1(t) * h_3(t)$
- Associative -  $h_1(t) * [h_2(t) * h_3(t)] = [h_1(t) * h_2(t)] * h_3(t)$

12. An inter-connection of LTI system is shown. The impulse responses are:  $h_1(n) = (2/3)^n [u(n) - u(n-6)]$ ,  $h_2(n) = \sin(n) * u(n)$  and  $h_3(n) = u(n+3) - u(n-3)$  as shown in figure. Let the impulse response of the over-all system from  $x(n)$  to  $y(n)$  be denoted as  $h(n)$ . Find the impulse response of the over-all system. by (Consider  $n = -20$  to  $+20$ )

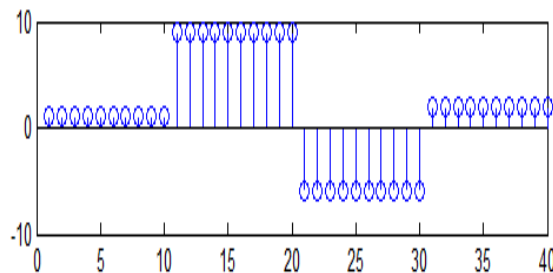


**figure**

13. Find convolution of following signal with “conv” function.  
 $y(n) = x_1(n) * x_2(n)$



$x_1(n)$



$x_2(n)$

- Find convolution of  $x_1(n) = [4 \ 3 \ 5 \ 2 \ 1 \ 5]$  and  $x_2(n) = [3 \ 6 \ 2 \ 4 \ 5]$  using “conv” function. (Verify theoretically and practically).
  - Find convolution of user defined signals without “conv” function and compare with “conv”.  
 $y(n) = x_1(n) * x_2(n)$
15. Discretization using different sampling rates and observing aliasing effect. Observing the effects of lower sampling rate and higher sampling rate on the signal.
16. Determine the transfer function  $H(S)$  and Impulse response  $h(t)$  of the system when,



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$$y(t) = e^{-t} - 2e^{-2t} + e^{-3t} \text{ and } x(t) = e^{-0.5t}$$

17. To determine the Z transform of different discrete-time signals.

**List of Open Source/learning websites:**

- <https://nptel.ac.in/courses/117/101/117101055/>  
entire syllabus
- <https://www.youtube.com/playlist?list=PLC6210462711083C4>  
entire syllabus (Video Lecture Series by IIT professors (Not Available in NPTEL) – "Signals and Systems" by Prof. S.C. Dutta Roy)
- <https://ocw.mit.edu/resources/res-6-007-signals-and-systems-spring-2011/lecture-notes/>  
entire syllabus

**List of Open Sources of software**

- SCILAB